

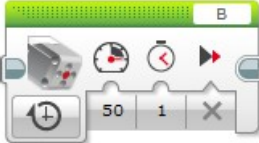

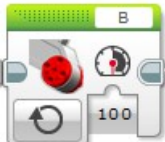


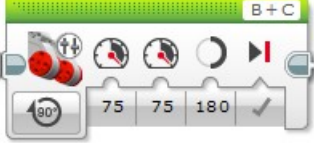






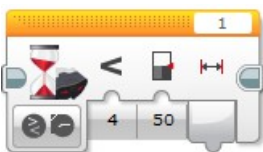

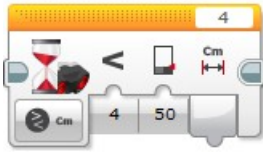


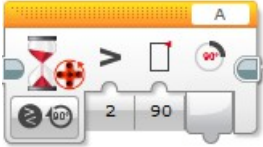






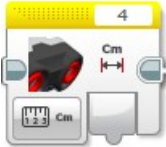

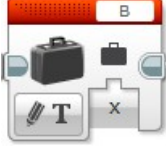

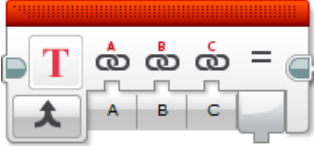
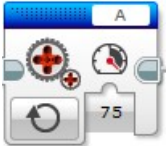
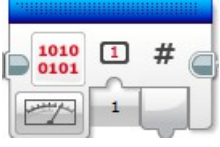



EV3-G	EV3 Basic
	Motor.Move("A", 75, 1*360, "True")
	Motor.Move("D", 75, 360, "True")
	Motor.Start("B", 50) Program.Delay(1000) Motor.Stop("B", "False")
	Motor.Stop("C", "True")
	Motor.Start("B", 100)
	Motor.StartSync("BC", 25, 25)
	Motor.StartSync("B", 0, 50) Program.Delay(1000) Motor.Stop("B", "False")
	Motor.MoveSync("BC", 75, 75, 180, "True")

	<p>LCD.Clear() LCD.Text(1, 0, 0, 2, "MINDSTORMS")</p>
	<p>LCD.Line (1, 50, 20, 130, 100)</p>
	<p>LCD.Clear() LCD.FillCircle(1, 100, 80, 40)</p>
	<p>LCD.Rect (1, 0, 0, 80, 80)</p>
	<p>LCD.Clear() LCD.Pixel (1, 80, 40)</p>
	<p>Speaker.Tone(100, 440, 1000) Speaker.Wait()</p>
	<p>Speaker.Note(75, "A5", 1000)</p>
	<p>Speaker.Stop()</p>
	<p>While "True" Speaker.Play(50, "Go.rsf") EndWhile</p>

	<p>EV3.SetLEDColor ("GREEN", "PULSE")</p>
	<p>EV3.SetLEDColor ("OFF", "NORMAL")</p>
	<p>Program.Delay(2000)</p>
	<p>Sensor.SetMode(3,2) While Sensor.ReadRawValue(3, 0) <> 5 EndWhile</p>
	<p>Sensor.SetMode(2,1) While Sensor.ReadRawValue(2, 0) >= 50 EndWhile</p>
	<p>Sensor.SetMode(1,1) A = Sensor.ReadRawValue(1, 0) While Sensor.ReadRawValue(1, 0) <= A + 10 EndWhile</p>
	<p>Sensor.SetMode(1,0) While Sensor.ReadPercent() >= 50 EndWhile</p>
	<p>Sensor.SetMode(4,1) While Sensor.ReadRawValue() >= 0 EndWhile</p>
	<p>Sensor.SetMode(4,0) While Sensor.ReadPercent() >= 50 EndWhile</p>

	<p>Sensor.SetMode(2,0) While ReadRawValue(2, 0) >= 90 EndWhile</p>
	<p>A = EV3.Time While EV3.Time <= A + 5000 EndWhile</p>
	<p>While Motor.GetCount("A") <= 90 EndWhile</p>
	<p>Sensor.SetMode(1,0) While Sensor.ReadPercent(1) = 0 EndWhile</p>
	<p>B = Buttons.Current</p>
	<p>Sensor.SetMode(3,2) D = Sensor.ReadRawValue(3, 0)</p>
	<p>Sensor.SetMode(4,0) X = Sensor.ReadPercent(4)</p>
	<p>C = Motor.GetCount("A")</p>
	<p>Z = EV3.Time</p>

	<p>Sensor.SetMode(4,0) S = Sensor.ReadRawValue</p>
	<p>A = 0</p>
	<p>B = "X"</p>
	<p>R = Sensor.ReadPercent(10)</p>
	<p>T = Text.Append("A","B") T = Text.Append(T,"C")</p> <p>ИЛИ</p> <p>T = Text.Append(Text.Append("A","B"),"C")</p>
	<p>Motor.Start("A",75)</p>
	<p>R = Sensor.ReadRawValue(1, 0)</p>
	<p>Program.End</p>

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